

Summary so far: we have obtained the heat equation from physical principle, then we added boundary condition, and solved the equilibrium problem.

- Goal now: To solve the (time-dependent) heat equation.

Remark: The homogeneous heat equation $u_t = k u_{xx}$ is linear, and thus it satisfies the Principle of Superposition:

"If u_1, u_2 solve the a linear homogeneous equation, then any linear combination $c_1 u_1 + c_2 u_2$ also solves it".

$$\begin{aligned} \text{Ex)} \quad \left. \begin{aligned} u_{1,t} &= k u_{1,xx} \\ u_{2,t} &= k u_{2,xx} \end{aligned} \right\} &\rightarrow (c_1 u_1 + c_2 u_2)_t = c_1 u_{1,t} + c_2 u_{2,t} = c_1 k u_{1,xx} + c_2 k u_{2,xx} = \\ &= k (c_1 u_1 + c_2 u_2)_{xx} // \end{aligned}$$

[Section 2.3] Heat equation with zero temperature at finite ends.

We will first solve the following problem:

$$\left. \begin{array}{ll} u_t = k u_{xx}, & 0 < x < L, t > 0 \text{ PDE} \\ u(0, t) = 0 & \text{BC} \\ u(L, t) = 0 & \\ u(x, 0) = f(x) & \text{IC} \end{array} \right\} \begin{array}{l} \text{linear and} \\ \text{homogeneous,} \\ \text{(including BC).} \end{array}$$

• Method of Separation of Variables

Key point: We look for solution that can be written in the

form $\boxed{u(x, t) = \phi(x) G(t)}$

Consequences:

$$u_t = k u_{xx} \Rightarrow \frac{1}{G(t)} \left(\phi(x) G'(t) \right) = k \frac{1}{\phi(x)} \left(\phi(x) G(t) \right) \Rightarrow$$

$$\Rightarrow \phi(x) G'(t) = k \phi''(x) G(t) \Rightarrow$$

$$\Rightarrow \left| \frac{1}{k} \frac{G'(t)}{G(t)} = \frac{\phi''(x)}{\phi(x)} \right|$$

Question: Notice that $\frac{1}{k} \frac{G'(t)}{G(t)}$ only depends on t , while $\frac{\phi''(x)}{\phi(x)}$ only depends on x . How is then possible that they are equal?

→ The conclusion is that both terms have to be constant, the same constant:

$$\frac{1}{k} \frac{G'(t)}{G(t)} = \frac{\phi''(x)}{\phi(x)} = -\lambda. \quad (\text{we choose } -\lambda \text{ for later convenience}).$$

called the "separation constant".

→ Therefore, we have to ODEs problems to solve:

$$\textcircled{1} \quad G'(t) = -\lambda k G(t)$$

$$\textcircled{2} \quad \phi''(x) = -\lambda \phi(x)$$

In summary, so far the steps are:

1. Let $u(x, t) = G(t)\phi(x)$.
2. Use the PDE to find an ODE for $G(t)$ and another for $\phi(x)$.
(depending on the separation constant $-\lambda$).

3. Time-dependent ODE: $G(t)$

$G'(t) = -\lambda k G(t)$ first-order linear homogeneous ODE with constant coefficients.

↓ $\boxed{G(t) = c e^{-\lambda k t}}$ (We will come back to this).

4. Boundary Value Problem: $\phi(x)$

$$\phi''(x) = -\lambda \phi(x)$$

In this step, we include the BC of the problem (notice, however, that we are not using the initial condition yet).

We had that $u(0, t) = 0$
 $u(L, t) = 0$ } so in terms of $G, \phi \rightarrow$

$$u(0, t) = \phi(0) G(t) = 0 \Leftrightarrow \begin{cases} \phi(0) = 0 \\ \text{or} \\ G(t) = 0 \text{ for all } t \text{ (trivial sol.)} \end{cases}$$

$$u(L, t) = \phi(L) G(t) = 0 \Leftrightarrow \begin{cases} \phi(L) = 0 \\ \text{or} \\ G(t) = 0 \text{ for all } t \text{ (trivial sol.)} \end{cases}$$

Therefore, the BVP to solve is:

$$\left. \begin{aligned} \phi''(x) + \lambda \phi(x) &= 0 \\ \phi(0) &= 0 \\ \phi(L) &= 0 \end{aligned} \right\} \text{BVP} \quad \begin{array}{l} \text{The } \uparrow \text{ solutions are called} \\ \text{eigenfunctions, with } \lambda \text{ the corresponding} \\ \text{eigenvalue.} \end{array}$$

non-zero

We need to distinguish four cases:

- 1) $\lambda = \alpha^2 > 0 \rightarrow r = \pm i\sqrt{\lambda} = \pm \alpha i$
- 2) $\lambda = 0 \rightarrow r = 0$ (double)
- 3) $\lambda = -\alpha^2 < 0 \rightarrow r = \pm \sqrt{\lambda} = \pm \alpha$
- 4) λ complex (we will not consider this: we will prove later that λ has to be real).

• Finding the eigenvalues and eigenfunctions:

1) $\lambda = \alpha^2 > 0$

Then, characteristic polynomial is $r^2 + \alpha^2 = 0 \rightarrow r = \pm \alpha i$, so

$$\phi(x) = c_1 \cos(\alpha x) + c_2 \sin(\alpha x).$$

Imposing the boundary conditions,

$$\left. \begin{aligned} \phi(0) &= 0 = c_1 \\ \phi(L) &= 0 = c_1 \cos(\alpha L) + c_2 \sin(\alpha L) \end{aligned} \right\} \rightarrow \begin{array}{l} c_2 = 0 \text{ (then } \phi \equiv 0) \\ \sin(\alpha L) = 0. \end{array}$$

$\underbrace{\hspace{10em}}_{\rightarrow}$

$$\sin(\alpha L) = 0 \Leftrightarrow \alpha L = n\pi \quad \text{with } n = 1, 2, \dots \Leftrightarrow$$

$$\Leftrightarrow \lambda = \left(\frac{n\pi}{L}\right)^2, \quad n = 1, 2, \dots$$

The corresponding eigenfunction is $\phi(x) = c_2 \sin\left(\frac{n\pi x}{L}\right)$

2) $\lambda = 0$

$$\phi''(x) = 0$$

$$\phi(0) = \phi(L) = 0 \left\{ \begin{array}{l} \rightarrow \phi(x) = c_1 x + c_2 \\ \phi(0) = c_2 = 0 \\ \phi(L) = c_1 L + c_2 = 0 \end{array} \right.$$

$$\left. \begin{array}{l} \phi(0) = c_2 = 0 \\ \phi(L) = c_1 L + c_2 = 0 \end{array} \right\} \rightarrow c_1 = c_2 = 0 \rightarrow \phi \equiv 0$$

So $\lambda = 0$ is not an eigenvalue.

3) $\lambda = -\alpha^2 < 0$

$$\phi''(x) - \alpha^2 \phi(x) = 0 \leadsto r^2 = \alpha^2 \leadsto r = \pm \alpha \leadsto \phi(x) = c_1 e^{\alpha x} + c_2 e^{-\alpha x}$$

which can also be written as

$$\phi(x) = c_3 \cosh(x) + c_4 \sinh(x).$$

$$BC \rightarrow \phi(0) = c_3 = 0$$

$$\phi(L) = \cancel{c_3} \cosh(L) + c_4 \sinh(L) = 0 \Leftrightarrow c_4 = 0 \left\{ \begin{array}{l} \rightarrow c_3 = c_4 = 0. \end{array} \right.$$

Thus,

$\lambda = -\alpha^2 < 0$ is not an eigenvalue.

In conclusion - the summary of step "4. BVP" is :

$$\left. \begin{array}{l} \phi''(x) + \lambda \phi = 0 \\ \phi(0) = \phi(L) = 0 \end{array} \right\} \text{ only has positive eigenvalues, given by } \boxed{\lambda_n = \left(\frac{n\pi}{L}\right)^2} \text{ with eigenfunction } \boxed{\phi_n(x) = \sin\left(\frac{n\pi x}{L}\right)}.$$

5. Product solutions.

We have obtained that

$$u(x,t) = \phi(x) G(t) \text{ is a solution of } \begin{cases} u_t = k u_{xx} \\ u(0,t) = u(L,t) = 0 \end{cases} \text{ if}$$

$$\left. \begin{array}{l} G(t) = c e^{-\lambda k t} \\ \phi(x) = \sin(\sqrt{\lambda} x) \end{array} \right| \text{ with } \lambda = \left(\frac{n\pi}{L}\right)^2, n=1, 2, \dots$$

That is, $\boxed{u(x,t) = \underset{\substack{\uparrow \\ \text{arbitrary constant}}}{B} \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}} \quad n=1, 2, \dots$

Remark: We haven't take into account the initial condition

$$u(x,0) = f(x).$$

6. Initial Value Problem (IVP).

Right now, our solution does not satisfy the initial condition:

$$u(x, 0) = f(x) \neq B \sin\left(\frac{n\pi x}{L}\right) \quad (\text{unless } f(x) \text{ happens to be a multiple of } \sin\left(\frac{n\pi x}{L}\right)).$$

Example: Solve

$$\left. \begin{aligned} u_t &= k u_{xx} \\ u(0, t) &= u(L, t) = 0 \\ u(x, 0) &= 4 \sin\left(\frac{3\pi x}{L}\right) + 7 \sin\left(\frac{8\pi x}{L}\right) \end{aligned} \right\}$$

Sol:

Notice that by linearity ("superposition principle"), we can split the problem in two:

$$\left. \begin{aligned} u_{1,t} &= k u_{1,xx} \\ u_1(0, t) &= u_1(L, t) = 0 \\ u_1(x, 0) &= 4 \sin\left(\frac{3\pi x}{L}\right) \end{aligned} \right\} \quad \left. \begin{aligned} u_{2,t} &= k u_{2,xx} \\ u_2(0, t) &= u_2(L, t) = 0 \\ u_2(x, 0) &= 7 \sin\left(\frac{8\pi x}{L}\right) \end{aligned} \right\}$$

The solution to the original problem is $u(x, t) = u_1(x, t) + u_2(x, t)$.

Now, we have the solution for each problem:

$$\left. \begin{aligned} u_1(x, t) &= 4 \sin\left(\frac{3\pi x}{L}\right) e^{-k\left(\frac{3\pi}{L}\right)^2 t} \\ u_2(x, t) &= 7 \sin\left(\frac{8\pi x}{L}\right) e^{-k\left(\frac{8\pi}{L}\right)^2 t} \end{aligned} \right\} \rightarrow u = u_1 + u_2$$

→ Principle of Superposition:

Since the problem was linear and homogeneous, and

$u(x,t) = B \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$ is a solution for $n=1, 2, \dots$,

any linear combination is also a solution:

$$u(x,t) = \sum_{n=1}^N B_n \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$

Remark: This allows for more general initial data:

$$u(x,0) = f(x) = \sum_{n=1}^N B_n \sin\left(\frac{n\pi x}{L}\right).$$

• Claim: [Chapter 3] (Fourier series)

"Any" function can be written an infinite linear combination of sines,

$$f(x) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right).$$

Therefore, the solution to our problem is:

$$u(x,t) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right) e^{-k\left(\frac{n\pi}{L}\right)^2 t}$$

2. Finding B_n : Orthogonality of Sines.

Under the assumption of the previous claim, how do we find the constants B_n so that

$$f(x) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right) ?$$

That is, given $f(x)$, how to compute B_n ?

• Proposition: Orthogonality of the (eigenfunctions) $\sin\left(\frac{n\pi x}{L}\right)$

$$\left| \int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = \begin{cases} 0 & m \neq n \\ L/2 & m = n. \end{cases} \right| \quad n, m = 1, 2, 3, \dots$$

Proof: Homework.

Let's see how to use this property to find B_n .

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Intuition: The functions $\sin\left(\frac{n\pi x}{L}\right)$ are the vectors of an orthogonal basis, and $f(x)$ is written as a linear combination of the basis vectors. The dot product here is defined as the integral over $[0, L]$.

$$\left\{ \vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \right\} \quad \left\{ \begin{array}{l} \vec{w} = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n \Rightarrow c_j = \frac{\vec{w} \cdot \vec{v}_j}{\vec{v}_j \cdot \vec{v}_j} \\ \vec{v}_i \cdot \vec{v}_j = 0 \quad i \neq j \end{array} \right. \quad \vec{w} \cdot \vec{v}_j = c_j \vec{v}_j \cdot \vec{v}_j$$

We start with

$$f(x) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right).$$

Multiply by $\sin\left(\frac{m\pi x}{L}\right)$: $f(x) \sin\left(\frac{m\pi x}{L}\right) = \sum_{n=1}^{\infty} B_n \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right).$

Integrate from $x=0$ to $x=L$:

$$\int_0^L f(x) \sin\left(\frac{m\pi x}{L}\right) dx = \sum_{n=1}^{\infty} B_n \underbrace{\int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx}_{= \begin{cases} 0 & \text{if } m \neq n \\ \frac{L}{2} & \text{if } m = n. \end{cases}} \Rightarrow$$

$$\Rightarrow \int_0^L f(x) \sin\left(\frac{m\pi x}{L}\right) dx = B_m \int_0^L \sin^2\left(\frac{m\pi x}{L}\right) dx \Rightarrow$$

$$\Rightarrow B_m = \frac{\int_0^L f(x) \sin\left(\frac{m\pi x}{L}\right) dx}{\int_0^L \sin^2\left(\frac{m\pi x}{L}\right) dx} = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{m\pi x}{L}\right) dx = B_m \parallel.$$